# SREEHARSHA PARUCHURI

## **Software Engineering | Deep Learning | Robotics**

@ sreeharsha0401@gmail.com

**J** +91 8106175505

n sreeharshaparuchuri

sreeharshaparuchur1

## **EXPERIENCE**

## Research Assistant

#### Advised by Dr. Madhava Krishna

**a** January 2020 - June 2022

Robotics Research Center, IIIT-H

- Working to jointly learn pose, depth and free-space in a self-supervised manner on indoor environments collected from Gibson using stereo vision and deep learning.
- Integrated laser depth data and monocular images to solve the absolute orientation problem between the laser and the camera using SLAM methods and Neural Networks with the KITTI dataset.
- Led the Vision and Navigation team for the ARTPARK robotics challenge along with building and testing a prototype robot for the final stage.

## Research Assistant

## Advised by Dr. Vinoo Alluri and Dr. Ponnurangam Kumaraguru

**Dec 2020 - June 2022** 

- Cognitive Science Lab, IIIT-H
- Worked on analysing the impact of lyrical regularities as an indicator of depressive music listening tendencies.
- Working on a multi-modal network to aid in early diagnosis of depression using online music listening habits.
- Using a data-driven approach to finding a correlation between the music listening habits and the social media engagements of an individual.

#### Computer Vision Intern

#### Advised by Dr. Amit Kale and Dr. Tejaswi Kasarla

May 2021 - Aug 2021

- Bosch Research Center, Remote
- Worked on a Research Project in collaboration with Diamler that dealt with Autonomous Driving using Laser, Image and Odometry data.
- Developed and tested online and offline algorithms for Multi-Object Tracking using laser data from the NuScenes dataset.

## **Teaching Assistant**

**ä** Jan 2021 - June 2022

● IIIT-H

- EC5.205.S21 Introduction to Coding Theory: Taught a class of 100+ students the fundamentals of applied Linear Algebra and Abstract Algebra with applications in signal processing.
- **CS7.503.M21** *Mobile Robotics*: Taught a class of 65+ graduate and undergraduate students the fundamentals of SLAM and Computer Vision. Taught Deep Learning basics in the Lab's summer school to 40 students.
- CS9.434.S22 Music, Mind and Technology: Head Teaching Assistant for a class of 100+ graduate and undergraduate students and developed assignments on music information retrieval.

# **RELEVANT COURSES**

Core: Data Structures and Algorithms, Compilers, Robotics: Planning and Navigation, Processor Architecture, Signal Processing Artificial Intelligence: Computer Vision, Statistical Methods in Al, Mobile Robotics, Topics in Applied Optimization

Mathematics: Probability and Random Processes, Linear Algebra, Introduction To Coding Theory, Introduction to Game Theory

# **EDUCATION**

# B.Tech (with honours) in ECE

- **a** Aug 2018 May 2022
- Honours in Computer Vision and Robotics
- Deans list (Monsoon 2020, Spring 2021)

# **PROJECTS**

## **ARTPARK Robotics Challenge**

- Represented the university and finished runners up in this national robotics competition by creating and deploying a full-stack software solution in ROS and Gazebo in C++ / Python.
- Developed the vision algorithms used to detect regions of interest via image processing and point cloud filtering techniques.

## Mini SQL Engine

- A Mini SQL engine using python, which can parse and run a subset of SQL queries using command line interface.
- Supports Select, aggregate functions, where conditions, group by, order by, distinct, limit with appropriate error handling.

#### Linux Shell

 Implemented a Linux Bash shell, a command line interpreter in C. Supports numerous bash commands along with piping, redirection, foreground and background processing.

## 3D interactive flying game

Built a 2D arcade game and a 3D flight simulator game in OpenGL 3.0 using graphics concepts such as texture mappings, rasterisation and lighting, with support for multiple camera views for resplendent gameplay.

## Paper Implementations

- Classical: GrabCut, Viola-Jones, Lane Detector, Gauss-Newton optimization, Seam-Carving.
- Learning: Context Encoders, Reflection removal, Pose-Graph Optimization.
- Please visit my GitHub for more projects.

# **SKILLS**

Languages: Python, C++, C, MATLAB, Java, Racket, GoLang, JavaScript, HTML/CSS Libraries: PyTorch, Tensorflow, Keras, Scikit-

Learn, OpenCV, Open3d, Jax Frameworks: Flask, Django, Node

Other: ROS, MongoDB, SQL, Git, Docker